TigerloT



Pressure Independent Control Valve--AHU Technical Data Sheet



TPF... Series

PICV-AHU

It can match with most of TW series actuators, which are unaffected by system pressure fluctuations, and have excellent flow regulation and balance functions.

Product Features

High Control Precision

Both control valve core and balancing valve core adopt straight travel design. Compared with rotary design, straight travel has higher control precision.

High Close-off DP, Low Leakage Rate

The valve has a higher close-off differential pressure, while the leakage rate is no more than 0.02% of Qmax.

Build-in Diaphragm Capsule and Connecting Pipe

The valve adopts the build-in diaphragm capsule and connecting pipe. It can avoid damaging during installation compared with external connecting pipe.

Anti-blocking Design

The balance structure of spring diaphragm significantly reduces the probability of blocking inside. Because of the lower requirement for water quality, it can easily deal with the water in heating pipeline.

High-quality Materials

The valve body is made of high-quality ductile iron material (EN-GJS-450-10), and the surface adopts electrostatic spraying craft, the body has better intensity and corrosion resistance.

Type Overview



| Series | TW1000 | TW1001 | TW3000 |
|-----------------------|--------|--------|--------|
| Actuator Rated Stroke | 30mm | 50mm | 50mm |
| Nominal Output Force | 1000N | 1000N | 3000N |

Icon



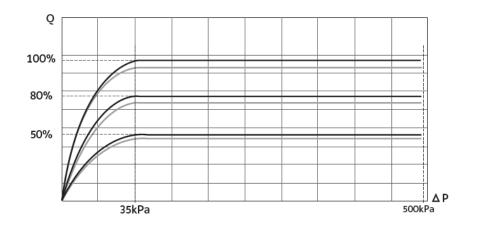




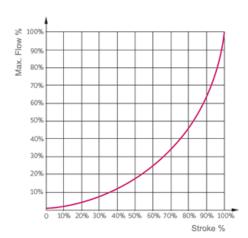
24V, Proportional & floating control TW1000-XD24-S.12 TW1001-XD24-S.14 TW3000-XD24-S.14

| | | | | ing control | | | |
|----------------------------|------------------|------------|-----------------|----------------|--------------|--------------|--------------|
| Valve Type | Туре | DN [mm] | Strokee [mm] | Qmax [m³/h] | ∆Ps [kPa] | ∆Ps [kPa] | ∆Ps [kPa] |
| | TPF32-2VGC-S.12 | DN32 | 20 | 7 | 400 | | |
| | TPF40-2VGC-S.12 | DN40 | 20 | 11 | 400 | | |
| | TPF50-2VGC-S.12 | DN50 | 20 | 13 | 400 | | |
| | TPF65-2VGC-S.12 | DN65 | 20 | 21 | 400 | | |
| PN16 | TPF80-2VGC-S.14 | DN80 | 40 | 28 | | 400 | |
| Medium temp.: -10~120°C | TPF100-2VGC-S.14 | DN100 | 40 | 50 | | 400 | |
| | TPF125-2VGC-S.14 | DN125 | 40 | 90 | | 400 | |
| | TPF150-2VGC-S.14 | DN150 | 40 | 145 | | 400 | |
| | TPF200-2VGC-S.14 | DN200 | 40 | 208 | | | 400 |
| | TPF250-2VGC-S.14 | DN250 | 40 | 240 | | | 400 |
| | TPF32-2VGD-S.12 | DN32 | 20 | 7 | 400 | | |
| | TPF40-2VGD-S.12 | DN40 | 20 | 11 | 400 | | |
| | TPF50-2VGD-S.12 | DN50 | 20 | 13 | 400 | | |
| | TPF65-2VGD-S.12 | DN65 | 20 | 21 | 400 | | |
| PN25 | TPF80-2VGD-S.14 | DN80 | 40 | 28 | | 400 | |
| Medium temp.: -10~120°C | TPF100-2VGD-S.14 | DN100 | 40 | 50 | | 400 | |
| -10 120 0 | TPF125-2VGD-S.14 | DN125 | 40 | 90 | | 400 | |
| | TPF150-2VGD-S.14 | DN150 | 40 | 145 | | 400 | |
| | TPF200-2VGD-S.14 | DN200 | 40 | 208 | | | 400 |
| | TPF250-2VGD-S.14 | DN250 | 40 | 240 | | | 400 |
| | | | | | | | |

Flow Characteristics

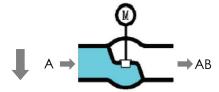


DP Flow Characteristic



Opening Flow Characteristic Equal-percentage

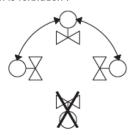
Structure Characteristics



While the valve stem reach lower limit position, the valve is closed.

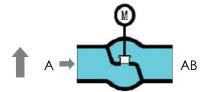
Installation Instruction

 Please pay attention to the valve mounting orientation! Medium is chilled/hot water, downward installation is forbidden.



3. Please note that the medium flow direction in valve should be consistent with the medium of pipeline!

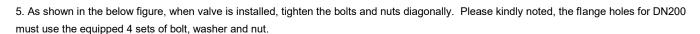


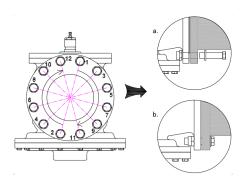


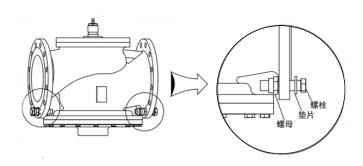
While the valve stem reach upper limit position, the valve is open.

2. Valve can be installed on the water supply pipe or return water pipe (installed on the return water pipe can control the water flow more smoothly, meanwhile the return water temperature is lower which can extends the service time of valve)

4. Filter and check valve are recommended to be installed before the valve.







Connection with Actuator

Valve and actuator can be assembled without any special tools, the attached Allen wrench will be enough. There is no need to do any manual adjustment after assembled. The actuator has the self-stroking function.

Notes: Prohibit installing outdoors to avoid PCB damage due to the condensation and water. Rain cover (TRAIN-1) and heating belt(THOT-3) are necessary in case of outdoor installation.



Loosen the slider and clip, then put the actuator on the valve body and keep the two connecting faces coinciding, fix the screws on the slit with Allen wrench.

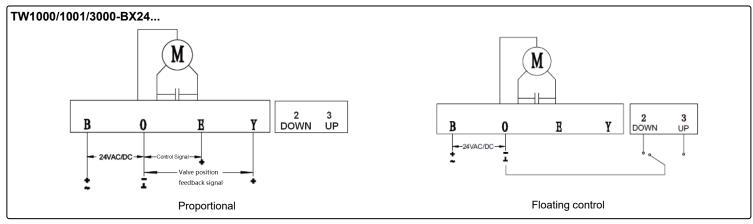


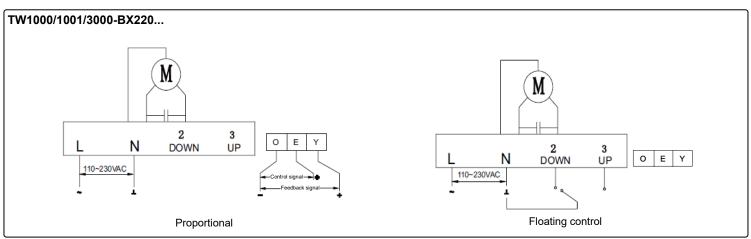
Install the slider on the actuator, then tighten the screws with Allen wrench.

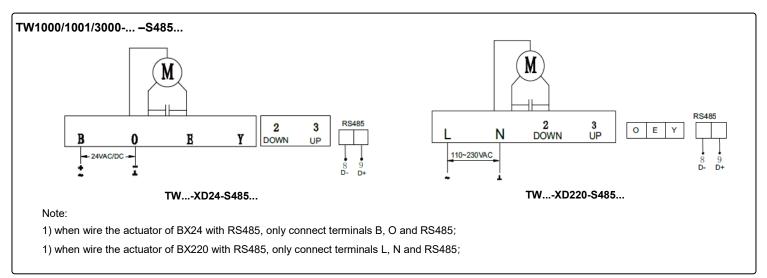


Complete the assembly of valve and actuator.

Wiring Diagram





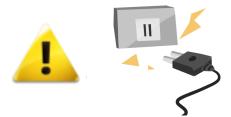




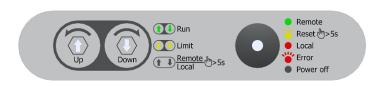
Terminals 4, 5, 6, and 7 are SPDT feedback , normally open contacts, with contact capacity \leq 30VDC. When the actuator runs to limiting position 0, terminals 4 and 5 will conduct and output dry contact feed-back. When the actuator runs to limiting position 1, terminals 6 and 7 will conduct and output dry contact feed-back.

Wiring Instruction

- 1. Please cut off power supply during wiring in order to ensure personal safety!
- 2. Carefully check the power voltage when wiring, wire according to the product parameter, if not, it may cause fire and endanger personal safety in severe case!
- 3. Open the cover when wiring, prohibit disassembling other spare parts!
- 4. After wiring, please install the cover to the original position to avoid electric shock!



Indicating Light



| Reset | Status | Description |
|--------|----------------|----------------|
| Green | Always | Normal mode |
| Red | Always | Local mode |
| Orange | Flashing | Testing stroke |
| Red | Quick flashing | Alarming |

| UP | Status | Description |
|--------|----------|----------------------------|
| Green | Always | Normal mode |
| Red | Always | Local mode |
| Orange | Always | Reach upper limit position |
| Red | Flashing | Alarming |

| DOWN | Status | Description |
|--------|----------|----------------------------|
| Green | Always | Normal mode |
| Red | Always | Local mode |
| Orange | Always | Reach lower limit position |
| Red | Flashing | Alarming |

Debugging Instruction

- A. Connect actuator and valve body, wiring according to wiring diagram.
- B. Automatic self-stroking (factory default setting): actuator will repeat automatic self-stroking when power on each time, the process is as follows:
- 1) The Reset yellow indicating light will keep flashing, actuator shaft extends to lower limit position firstly and then, it retracts to upper limit position, actuator will not be controlled by signal by this time.
- 2) Reset yellow light stop flashing, self-stroking stops. By then, actuator running direction can be controlled by control signal.
- 3) If the Reset red light is quick flashing during the self-stroking, it means the self-stroking status is not correct and the actuator will start alarming. The actuator can not match with the valve's max. stroke.

Remarks: If you don't need automatic self-stroking function , you can set the 7th switch to OFF, it will change into manual self-stroking.

C. Manual self-stroking function: If self-stroking is need in a power-on state, press down the Reset button over 5 seconds, and then the actuator starts self-stroking. The phenomenon is the same as step B.

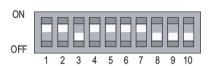
DIP Switch Instruction

| Switch | Function | Descri | ption |
|--------|-------------------------------|--------|--|
| S1-1 | Starting of control/ | ON | 4~20mA or 2~10VDC |
| 31-1 | feedback signal | OFF | 0~20mA or 0~10VDC |
| S1-2 | Type of control | ON | Current signal |
| 31-2 | signal | OFF | voltage signal |
| S1-3 | Type of input | ON | voltage signal |
| 31-3 | Type of input impedance | OFF | Current signal |
| S1-4 | Type of feedback | ON | Current signal |
| 31-4 | signal | OFF | voltage signal |
| S1-5 | Operating mode OFF | | When control signal increases, actuator shaft extends; When control signal decreases, actuator shaft retracts. |
| 01-0 | | | When control signal increases, actuator shaft retracts; When control signal decreases, actuator shaft extends. |
| S1-6 | Losing control | | When lose control signal (voltage type or current type), actuator will provide a min. control signal internally. |
| 31-0 | Losing control signal mode | OFF | 1)When lose control signal (voltage type), actuator will provide a max. control signal internally. |
| | | | 2)When lose control signal (current type), actuator will provide a min. control signal internally. |
| S1-7 | Self-stroking mode | ON | Power on each time, self-stroking starts automatically. |
| | | OFF | Self-stroking starts only when press the self-stroking button manually. |
| S1-8 | Control type | ON | 3-position type |
| 31-0 | (when S1-9 is OFF) | OFF | Proportional type |
| S1-9 | Control mode | ON | RS485 interface control (ModBus protocol) |
| 31-8 | Control mode | OFF | Proportional type and 3-position type |
| S1-10 | Chood | ON | High speed |
| 31-10 | Speed | OFF | Low speed |

Function Introduction

Modulating

Control signal/feedback signal: 4~20mA



Control signal/feedback signal: 0~10VDC



When equipped with PICV, terminal B, O is power input, actuator can be controlled by connecting terminal O, E, as shown above:

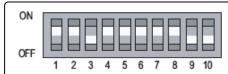
Control signal at terminal O, E increasing: actuator shaft retracts, valve stem extends, valve tends to open.

Control signal at terminal O, E decreasing: actuator shaft extends, valve stem retracts, valve tends to close.

Control signal at terminal O, E has no changing, actuator shaft and valve stem stay in present position.

When voltage (or current) signal is disconnected, this is equivalent to input a min. control signal, actuator shaft extends, valve closed.

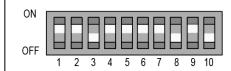
Floating control



When Dip switch S1-8 is on, it is 3-position type. Terminals B, O is power input, control the actuator by the switch O, UP, DOWN:

- O, UP connected: actuator shaft retracts, and valve stem extends
- O, DOWN connected: actuator shaft extends, and valve stem retracts

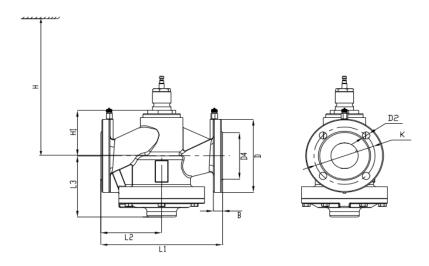
RS485 Bus Communication



When Dip switch S1-9 is on, it is RS485 Bus communication type. Terminals B, O is power input, remote control by terminal 8,9:

Actuator can be controlled remotely by RS485 bus communication, actuator supports ModBus protocol. Notes: Terminals O, E, Y, UP, DOWN doesn't work by this time!

Dimension



• PN16

| DN | B (mm) | D (mm) | D2 (mm) | D4 (mm) | K (mm) | L1 (mm) | L2 (mm) | L3 (mm) | H1 (mm) | H (mm) | Valve W. Kg |
|-----|-----------|-----------|------------|------------|-----------|------------|------------|------------|------------|-----------|-------------------|
| 32 | 18 | 140 | 4-19 | 76 | 100 | 180 | 90 | 130 | 84 | 399 | 15 |
| 40 | 18 | 150 | 4-19 | 84 | 110 | 200 | 100 | 131 | 89 | 404 | 17 |
| 50 | 20 | 165 | 4-19 | 99 | 125 | 230 | 115 | 136 | 95 | 410 | 19 |
| 65 | 22 | 185 | 4-19 | 118 | 145 | 290 | 145 | 155 | 115 | 430 | 28 |
| 80 | 24 | 200 | 8-19 | 132 | 160 | 310 | 155 | 167 | 148 | 483 | 36 |
| 100 | 22 | 220 | 8-19 | 156 | 180 | 350 | 175 | 181 | 150 | 485 | 54 |
| 125 | 26 | 250 | 8-19 | 184 | 210 | 400 | 200 | 197 | 163 | 498 | 68 |
| 150 | 24 | 285 | 8-23 | 211 | 240 | 480 | 240 | 222 | 198 | 533 | 89 |
| 200 | 24 | 340 | 12-23 | 266 | 295 | 500 | 250 | 245 | 180 | 525 | 140 |
| 250 | 26 | 405 | 12-28 | 319 | 355 | 600 | 300 | 277 | 210 | 555 | 207 |

• PN25

| DN | B (mm) | D (mm) | D2 (mm) | D4 (mm) | K (mm) | L1 (mm) | L2 (mm) | L3 (mm) | H1 (mm) | H (mm) | Valve W. Kg |
|-----|-----------|-----------|------------|------------|-----------|------------|------------|------------|------------|-----------|-------------------|
| 32 | 18 | 140 | 4-19 | 76 | 100 | 180 | 90 | 130 | 84 | 399 | 16 |
| 40 | 18 | 150 | 4-19 | 84 | 110 | 200 | 100 | 131 | 89 | 404 | 18 |
| 50 | 20 | 165 | 4-19 | 99 | 125 | 230 | 115 | 136 | 95 | 410 | 21 |
| 65 | 22 | 185 | 8-19 | 118 | 145 | 290 | 145 | 155 | 115 | 430 | 30 |
| 80 | 24 | 200 | 8-19 | 132 | 160 | 310 | 155 | 167 | 148 | 483 | 38 |
| 100 | 22 | 235 | 8-23 | 156 | 190 | 350 | 175 | 181 | 150 | 485 | 57 |
| 125 | 26 | 270 | 8-28 | 184 | 220 | 400 | 200 | 197 | 163 | 498 | 73 |
| 150 | 24 | 300 | 8-28 | 211 | 250 | 480 | 240 | 222 | 198 | 533 | 94 |
| 200 | 24 | 360 | 12-28 | 274 | 310 | 500 | 250 | 245 | 180 | 525 | 145 |
| 250 | 26 | 425 | 12-31 | 330 | 370 | 600 | 300 | 277 | 210 | 555 | 216 |

Technical Parameters

| Functional data-Valve | |
|-----------------------|-------------------------------------|
| Nominal size | DN50-DN250 |
| Nominal pressure | PN16 / PN25 |
| Flow characteristics | Equal percentage |
| Leakage rate | ≤0.02% Qmax |
| Medium temperature | -10~120℃ |
| Medium | Chilled/hot water, glycol under 50% |
| Connection standard | Flanged connection ISO7005-2 |

| Functional data–Actuator | |
|--|---|
| Rated Force | 1000N / 3000N |
| Operating Voltage TWXD24 TWXD220 | 24VAC±15%, 24VDC±15% 110VAC-220VAC±15% |
| Sensitivity | Modulating: 0.8% RS485: 0.2% (default setting) |
| Blind Zone (only for modulating type) | 2% (default setting) |
| Impedance (only for modulating type) Voltage Input Impedance Current Input Impedance | >100K <0.2K |
| Load requirements (only for modulating type) Voltage input impedance Current input impedance | >2K <0.5K |
| Degree of protection | IP65 |
| cable bond | PG13.5 |
| Lifetime | 10 thousand cycles |

| Valve spare parts mater | als |
|-------------------------|----------------------------|
| Valve body | Ductile iron EN-GJS-450-10 |
| Valve stem | Stainless steel |
| Valve core | Stainless steel |
| Sealing ring | PTFE |
| Diaphragm | EPDM |

| Actuator spare parts materials | |
|--------------------------------|----------------------|
| Cover | PC |
| Shell | Aluminum die casting |
| Bracket | Stainless steel |
| Base | Aluminum die casting |

| Environmental condition | |
|-------------------------|---------------------------|
| Running | |
| Ambient temperature | -25~+65℃ |
| Ambient humidity | ≤95% RH, non-condensation |
| Storage | |
| Ambient temperature | -40~+65℃ |
| Ambient humidity | ≤95% RH, non-condensation |

| • Certificates | |
|----------------------|--------------------------------|
| CE certificate | |
| PED directive | 2014/68/EU |
| System certification | |
| QMS | GB/T19001-2016 / ISO9001:2015 |
| EMS | GB/T24001-2016 / ISO14001:2015 |
| OHSAS | GB/T45001-2020 / ISO45001:2018 |



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TigerloT







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